

Operational Use of RNZ Jetty 3: Interaction with Proposed Berths 4 and 5 at Northport

Introduction

This analysis was carried out in September by Northport Ltd using their bridge simulator onsite at the port facility. The purpose of this study is to understand the potential impact the proposed Northport berths 4 and 5 would have on a small coastal tanker/ bunker barge arriving and departing RNZ Jetty 3 For this study, the existing Channel was used with the proposed new berths 4 and 5.

Design Ship

A new model based on the Bunker Barge Awanuia in a ballasted (4m) and loaded condition (6m) was developed. Awanuia is an 80m Product Tanker used as a bunker barge. She is fitted with 2 azimuthing thrusters aft and a bowthruster. The simulated design ship was tested in the Marsden simulation area (Marsden 5A) using the latest tidal data provided by Metocean.

Simulations

| Run | Maneuver | Tide HW | Wind | Vessel | BT | Comment | Master |
|--------|-----------|----------|------|--------|------|---|--------|
| Number | | | | | Used | | |
| | | | | Draft | | | |
| 001 | Arrival | HW -3HRS | E20 | В | Y | Controlled arrival | BG |
| 002 | Departure | HW -3HRS | E20 | В | Y | Managed departure no problem | BG |
| 003 | Arrival | HW -3HRS | SW10 | В | Y | Controlled all ok | RO |
| 004 | Arrival | HW -3HRS | SW20 | В | Y | No problem. | RO |
| 005 | Arrival | HW -3HRS | SW25 | В | Y | Max ROT 30 g/m on arrival. No issues | RO |
| 006 | Arrival | HW -3HRS | SW30 | В | Y | Able to balance forces. Possible fendering on | RO |
| | | | | | | western edge of RNZ Jetty to protect | |
| 007 | Arrival | HW -3HRS | SW30 | В | Y | No problems controlling into berth | RO |
| 008 | Departure | HW -3HRS | N20 | L | Y | No problems when departing berth | RO |
| 009 | Departure | HW -3HRS | N30 | L | Y | No problems when departing berth. Leads | RO |
| | | | | | | of distance off berth 5 | |
| 010 | Departure | HW -3HRS | SW30 | L | Y | Not as much effect from wind due loaded condition | RO |
| | | | | | | | |
| 011 | Departure | HW -3HRS | NE30 | L | Y | No problems with the departure | RO |
| 012 | Departure | HW 3HRS | SW20 | L | Y | All managed ok | RO |
| 013 | Departure | HW 3HRS | SW30 | L | Y | Controlled departure. Important to | RO |
| | | | | | | define the impact on the ebb tide | |
| | | | | | | | 1 |



| 014 | Departure | HW 2HRS | SW15 | L | Y | Vessel departed RNZ3 with only one POD available (Port). Departure was slow but controlled. Emergency condition. No tug used | BG |
|-----|-----------|---------|------|---|---|---|----|
| 015 | Departure | HW 2HRS | NE10 | L | Y | Vessel departed RNZ3 with only one POD available (Port). Departure was slow but controlled. Emergency condition. No tug used | BG |



Pilot Card



28th September 2020

| | PILOT CA | RD | |
|--|------------------------------|----------------------------------|----------|
| | AWANUIA PARTICI | JLARS | FORM 2.7 |
| Call Sign : ZMA2137 | | | |
| Displacement (MT) : | DWT (MT) | Year Built : 2009 | |
| pross Tonnage : 2747 | Net (Tonnage : 1160 | | |
| ength Overall (m) : 79.90 | Breadth (m): 15.0 | Bulbous Bow : Yes | |
| raught (m): Fwd - | Aft : | Amidships : | |
| 15.0m | 41.8m | Air Draught |) I |
| 17.05m eparallel body at Wi Loaded 36.4r Ballast 34.4r | | + | _ |
| | Maximun | Power : 1080 kW per Engine | |
| ype of Engine : 2 x Wartsila Ingines Run at Constant Spe Clutched to Azipod Drive Unit | 6L20 Deisel ed (1000 RPM) | 2160 kW Total | |
| itch Variable ahead and aste | rn Pods turr | n thru 360 Deg Azimuth | |
| 00 % Pitch Astern is 50% Po zimuth | wer, for maximum aster | n power pods must be turned to | 180 Deg |
| o NOT Turn Pods through 2 zimuth Clutches/Pitch Contr | 70 Deg Azimuth - oppos ol | ed thrust from pods may damag | je |
| peed can be infinitely varied | between 0 and 11 Knots | s through use of Pitch Controls | |
| ne engines are not operated | in any critical range | | |
| e Maximum Number of Co unning whilst manouvering | nsecutive Starts is irrelev | vant as the Engines are continue | ous |

Time full ahead to full astern (sec) : 20 Secs Time Limit Astern (sec) : Unlimited

| | Pag | je 2 | | form 2 | 2.7 [Pilot Card].xls | |
|--|--|--|--------------------------------------|--------------|----------------------|--|
| STEERING Azipod Drive | | | | | | |
| Time hard over to hard over : 2 Rudder angle for Neutral effect | 5 sec; Pod from 90 De (deg) : Zero | g to 270 De | g thru 0 De | 9 | | |
| Propellers (nos) : 2 | Direction of turn : Inward Turning Controllable Pitch | | | | | |
| Thrusters (nos) : | 1 Bow Power : 300 KW | | | | | |
| Steering idiosynorasies : Steer require large pod angles if ship Steering with stern way at abov | Stern Power : - Azipo age while reducing spee speed is too far above e 4 knots requires large | ods - up to 2 d from >4 k propellor sp pod angles | 2180 kW inots may b eed. i. | e sluggish a | and | |
| EQUIPMENT CHECKED AND | READY FOR USE : | | Checked 0 | ok 🖌 | | |
| Anchors : | Cleared Away : | | | | | |
| Whistle : | | | | | | |
| Flags : | | | | | | |
| X Band Radar : | ARPA : | | | | | |
| S Band Radar : | ARPA : | | | | | |
| Speed Log : | Water / Ground | | | | | |
| Single Axis / Dual Axis | | | | | | |
| Echo Sounder : | | | | | | |
| Transducer : | | | | | | |
| Electronic Position Fixing : Tran | nsas Sailor 3000 based | on GPS | | | | |
| Compass System | Gyro Compass Error | (deg) : | | | | |
| Steering Gear : | Number of Power Un | its in Use : | 2 Per Pod | | | |
| Rudder / RPM / ROT Indicators | | | | | | |
| Engine Telegraphs : | | | | | | |
| VHF: | Mooring Winches & L | ines : | | | | |
| Equipment Operational Defects | | | | | | |
| Other Important Details : Vessel Inerted / Not Inerted / G | as Free / Not Gas Free | / In Ballast | / Loaded W | 'ith : | | |

Master

Pilot

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Simulation Run Plots Arrivals



Simulation Run Plots Departures



Simulation Run Plots Departures with One POD Emergency



Report 2020006



Conclusion

From the simulations it was seen that the design vessel could continue with its existing operations with minimal impact from the proposed new Northport Berths 4 and 5. The following points can be noted

1. Departures will be assisted by the positioning of a set of traditional leads on the beach between Berth5 Northport and Refining NZ. Coordinates (WGS 84) for the leads are

Front Lead 35° 50.21509'S 174° 29.8076'E Rear Lead 35° 50.24268'S 174° 29.8212'E

- 2. Fendering on the western side of the Refining NZ Berthing Dolphins will help prevent damage to the RNZ berth structure and the ship in the unlikely event of an emergency.
- 3. Tidal streams in the vicinity of RNZ Jetty 3 should be studied for possible impact of the new Northport Berths particularly the ebb stream. Worst case tidal streams were modelled for this simulation study.

References

- 1. ABS Vessel_Maneuverability_Guide_e-Feb17.pdf
- 2. Wheelhouse Poster MT Awanuia
- 3. Interview with Richard Oliver ex Master Awanuia