

Design Modelling

Oakura Catchment (M02)

Northland Regional Council

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CONTENTS

1	PROJECT OVERVIEW	3
2	STUDY AREA	5
3	DESIGN MODELLING	7
3.1	Overview	7
3.2	Model Parameters	7
3.2.1	Rainfall Intensity-Duration-Frequency	7
3.2.2	Design Rainfall Temporal Patterns	8
3.2.3	Losses	10
3.2.4	Boundaries	13
4	MODELLING RESULTS	14
4.1	Modelled Result Processing/Filtering	14
5	VERIFICATION OF DESIGN FLOWS	19
5.1	Regional Estimation Methods	20
5.1.1	NIWA New Zealand River Flood Statistics Portal	20
5.1.2	SCS method	20
5.1.3	Rational Method	21
5.2	Verification Results	21
6	SUMMARY	24

LIST OF FIGURES

Figure 1-1	Model delineation	4
Figure 2-1	Study area	6
Figure 3-1	Example of design rainfall grid (12-hour, 1% AEP rainfall) for M02	8
Figure 3-2	Temporal pattern for design rainfall of 12-hour, 1% AEP event	10
Figure 3-3	Hydraulic model material layer	12
Figure 4-1	Design modelling of 1% flood depth	15
Figure 4-2	Design Modelling of 1% AEP flood velocity	16
Figure 4-3	Design modelling of 1% AEP Flood hazard	17
Figure 4-4	Design modelling of 1% AEP flood depth zoomed at a township	18
Figure 5-1	Available streamflow gauges within Oakura catchment	19
Figure 5-2	Verification of design modelling results against hydrological estimates	23

LIST OF TABLES

Table 3-1	Key Modelling Information	7
Table 3-2	1% AEP Design rainfall depth	10
Table 3-3	Design model parameters	11
Table 4-1	Flood hazard classification	14
Table 5-1	Summary of 1% AEP peak flow comparison	22



1 PROJECT OVERVIEW

Overview

Water Technology was commissioned by Northland Regional Council (NRC) to undertake a region-wide flood modelling study. The study area encompassed the entire Northland Regional Council area which covers an area of over 12,500 km², with the exclusion offshore islands. The aim of this project was to map riverine flood hazard zones across the entire Northland region and update existing flood intelligence.

Modelling approach

This project used a 2D Direct Rainfall (also known as Rain on Grid) approach for hydraulic modelling and has provided flood extents for a defined range of design storms. The hydraulic modelling software TUFLOW was used. TUFLOW is a widely used software package suitable for the analysis of flooding. TUFLOW routes overland flow across a topographic surface (2D domain) to create flood extent, depth, velocity and flood hazard outputs that can be used for planning, intelligence and emergency response. The latest release of TUFLOW offers several recent advanced modelling techniques to improve modelling accuracy which where practical, were tested and adopted in this project.

This study delineated and modelled 19 catchments, shown in Figure 1-1. To validate the adopted methodology and model parameters used in the design modelling, 9 catchments were calibrated against recent (and historic) flood events. The calibration/validation methodology is documented in a standalone report *NRC Riverine Flood Mapping - Calibration Report – R01* and is referred to throughout this document as the *Calibration Report*.

This report documents the design modelling methodology for Oakura Catchment (M02), noting that this catchment was not calibrated, however, model parameters reflected regional parameters and assumptions relied upon for Catchments M01, M13 & M14 which were calibrated and are located within close proximity to Catchment M02.

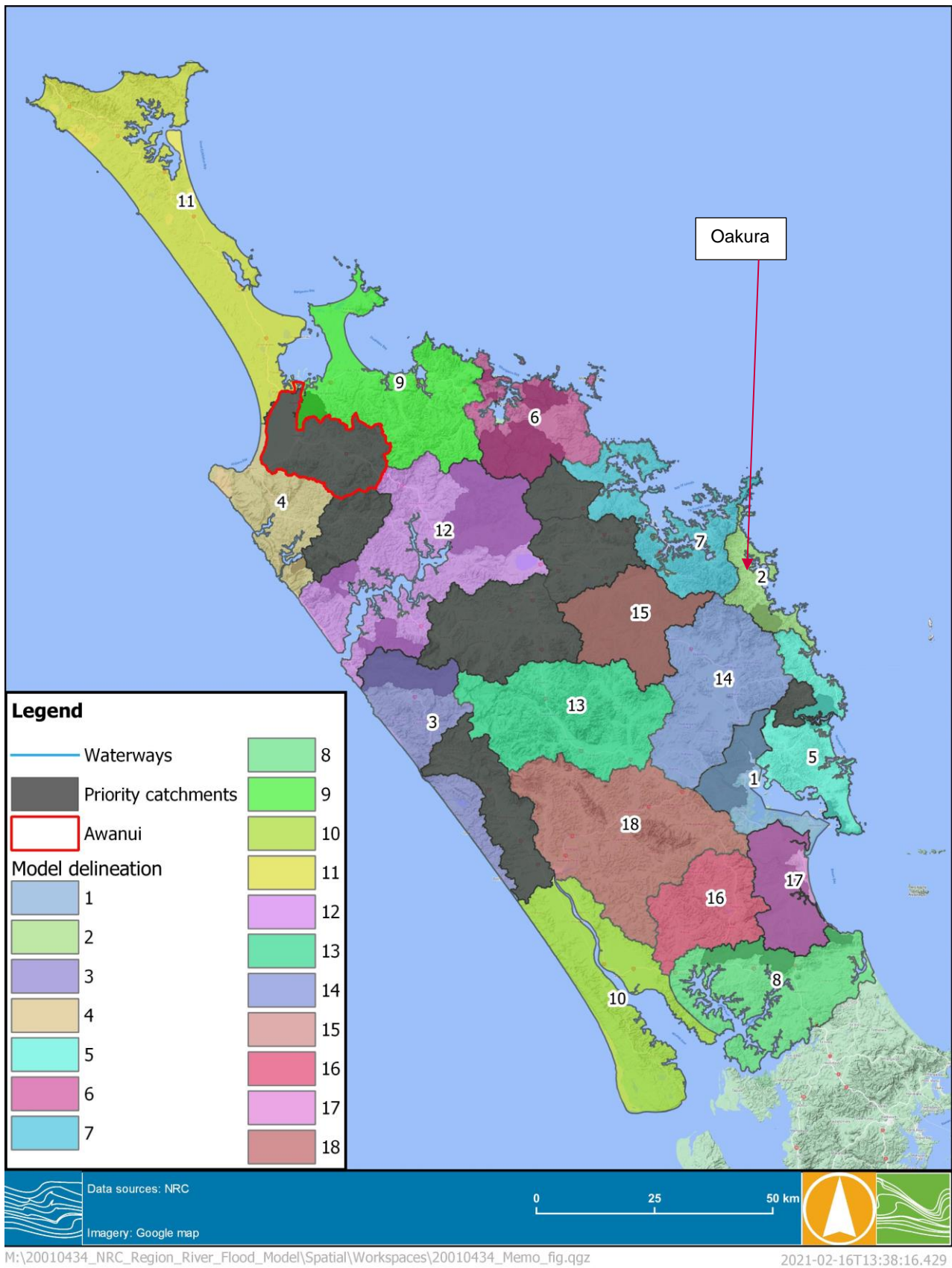


FIGURE 1-1 MODEL DELINEATION



2 STUDY AREA

The Model 02 catchment is coastal catchment, covering a total area of approximately 164 km² with Whangaruru, Oakura and Helena Bay its main townships. Waterways within the catchment generally consist of short sharp reaches. The only named waterway identified is Racehorse River, while there are various unnamed waterways discharging into the east coast. Figure 2-1 displays the study area of the catchment Model 02.

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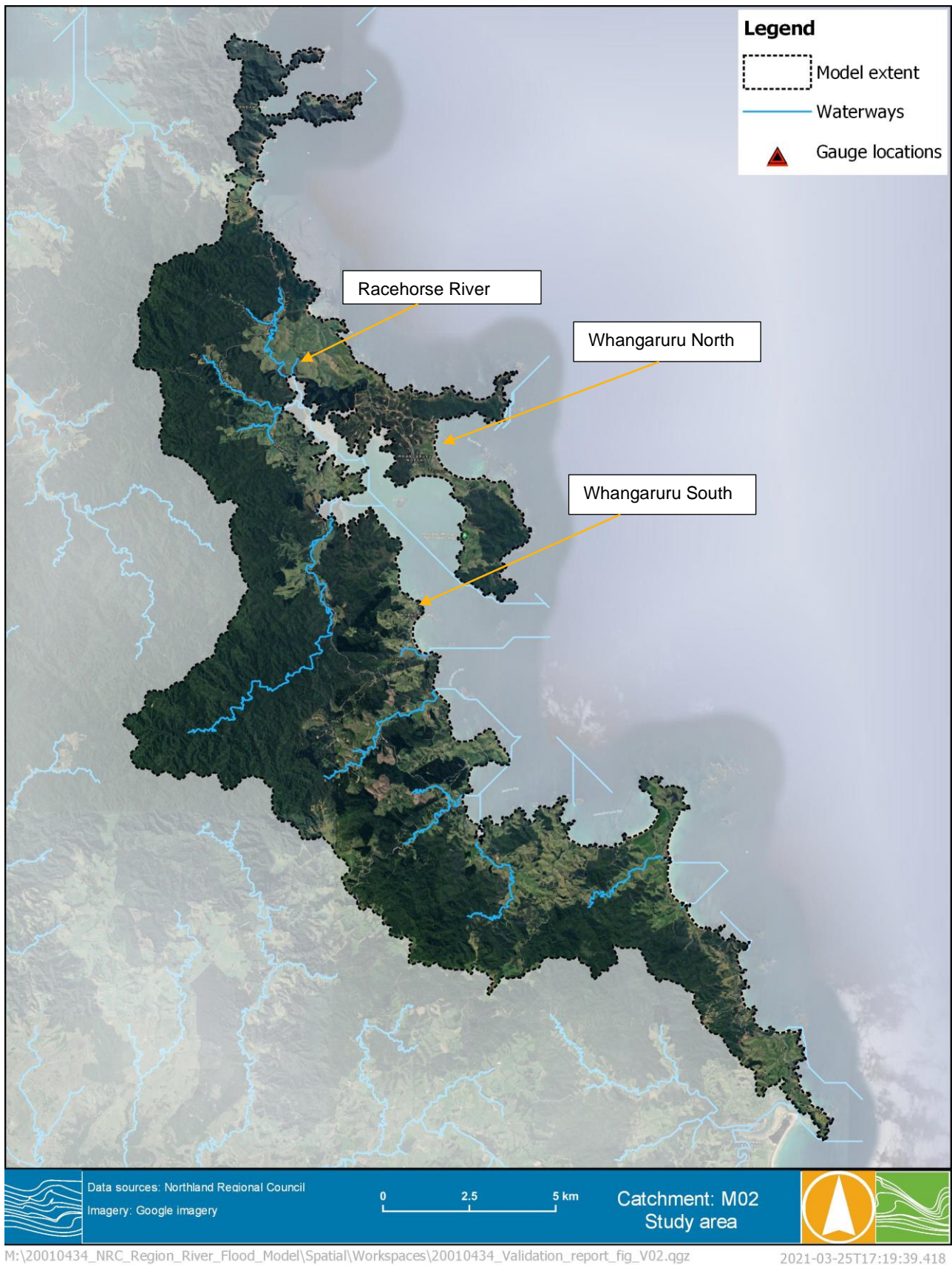


FIGURE 2-1 STUDY AREA



3 DESIGN MODELLING

3.1 Overview

A hydraulic model (TUFLOW) of the Oakura catchment (M02) was constructed to model overland flooding. A range of storm durations were run and results for each Annual Exceedance Probability (AEP) event were enveloped to ensure the critical duration was well represented across each part of the study area. The merged results captured the maximum flood level and depth of the range of design event durations modelled.

Table 3-1 and the following sections detail the key modelling information used in the development of the hydraulic model.

TABLE 3-1 KEY MODELLING INFORMATION

Terrain data	NRC 1m LiDAR without filling of sinks but includes the “burning of creek alignments’ through embankments
Model type	Direct rainfall model
Model build	Build: 2020-10-AA-iSP-w64
Rainfall	See Sections 3.2.1 and 3.2.4
Losses	See Section 3.2.3
Boundaries	See Section 3.2.4
Modelling solution scheme	TUFLOW HPC (adaptive timestep)
Modelling hardware	GPU
Modelling technique	Sub-grid-sampling (SGS)
Model grid size	10m with 1m SGS

3.2 Model Parameters

A range of model parameters were adopted, based on the calibration of catchments (i.e. M01, M13, M14 and M15) in the Whangarei District, M14 is adjacent to M02 and is found to provide suitable regional parameters. Details of these are outlined below.

3.2.1 Rainfall Intensity-Duration-Frequency

Intensity-Duration-Frequency (IDF) tables were developed by NIWA through the High Intensity Rainfall Design System (HIRDSV4)¹. Design rainfall totals for durations from 10 minute up to 120 hours were developed for design modelling and were developed at 179 rainfall gauge sites across the wider study area. The IDF tables cover a range of magnitude events from 1 in 1.58 ARI through to 1 in 250 ARI along with climate change predictions (Representative Concentration Pathway 4.6, 6 & 8.5) up to the year 2100. For this catchment, four rainfall gauges were used with a spatially weighted grid of rainfall totals created for design modelling. Figure 3-1 shows the 12-hour cumulative rainfall grid for the 1% AEP event along with the rainfall gauge locations used to create the grid.

¹ Accessed via <https://hirds.niwa.co.nz/>

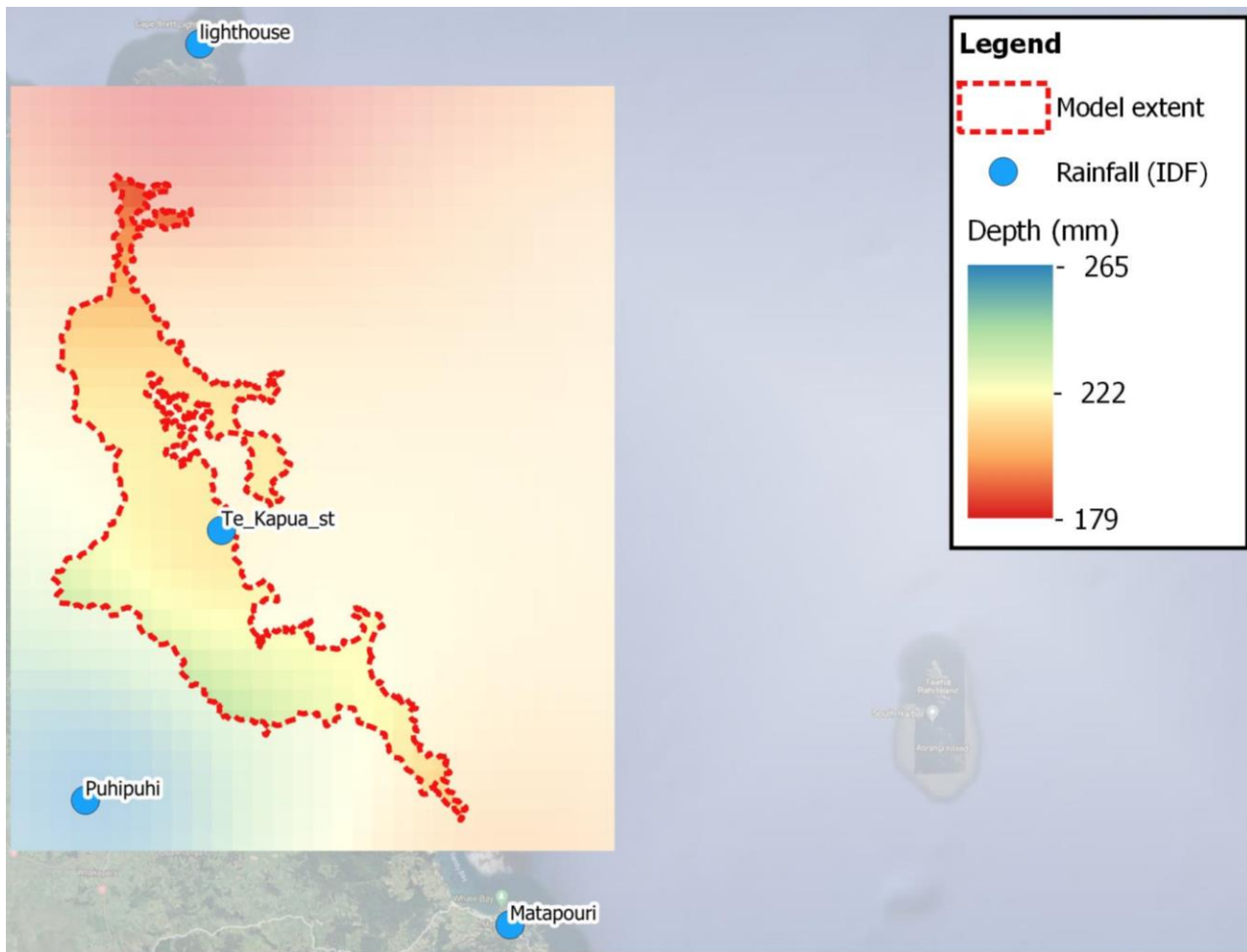


FIGURE 3-1 EXAMPLE OF DESIGN RAINFALL GRID (12-HOUR, 1% AEP RAINFALL) FOR M02

3.2.2 Design Rainfall Temporal Patterns

Design temporal patterns (rainfall hyetographs) were provided by NRC for design modelling. These were developed by HIRDS and subsequently reviewed as part of a project undertaken by Macky & Shamseldin (2020)². The project aimed to provide multiple design hyetographs and a better representation of rainfall variability across the Northland region, replacing the single set of design hyetographs previously developed.

The HIRDS design temporal pattern is recommended for design modelling of Northland catchments². Hence, the design hyetographs for the rainfall gauges were developed using the rainfall IDF data at available rainfall gauges for the catchment. Although a 12-hour hyetograph is suitable for design modelling for most Northland catchments as suggested², a range of durations were selected; including 1-hour, 6-hour, 12-hour and 24-hour for each of the following AEPs; 10%, 2% and 1% AEP to ensure that the event critical duration was identified across the catchment. The shorter durations were critical in the upper parts of the catchment, while the longer 24-hour durations were critical in the lower catchment, where flood volumes are generally the predominant factor in generating peak flood levels.

Table 3-2 summarises the 1% AEP rainfall depth (based on IDF from HIRDSV4) for different event durations at each rainfall gauge and Figure 3-2 shows the design cumulative rainfall across the different gauges for the

² Macky & Shamseldin (2020) - Northland Region-wide Hyetograph review



12-hour duration event. Considering a single temporal pattern is assigned (i.e. HIRDS hyetograph), the proportional amount of rainfall applied through time for a given duration (e.g., 6-hour) is generally consistent (as shown in Figure 3-2) across the catchment area.

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TABLE 3-2 1% AEP DESIGN RAINFALL DEPTH

Gauge location	1% AEP (mm)			
	1-hour	6-hour	12-hour	24-hour
Cape Brett lighthouse (A54131)	72	136	166	197
Matapouri (A54551)	75	160	202	247
Oakura Bay at Te Kapua Street	79	175	224	281
Whakapara at Puhi Puhi (545201)	82	218	295	382

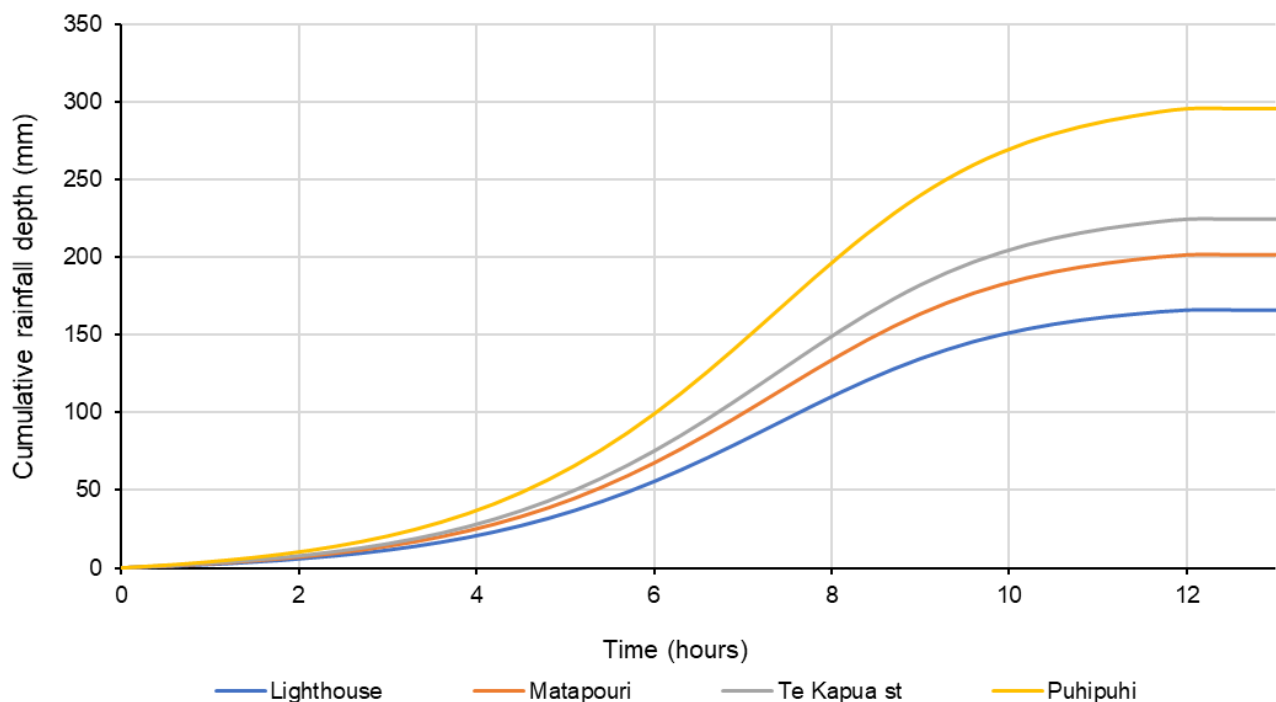


FIGURE 3-2 TEMPORAL PATTERN FOR DESIGN RAINFALL OF 12-HOUR, 1% AEP EVENT

A climate change scenario (for the 1% AEP events) was modelled for the 2081-2100 timeframe, for the RCP 8.5. This is based on the increases in rainfall intensity of 35%, 30%, 26% and 22% respectively for 1-hour, 6-hour, 12-hour and 24-hour duration events.

3.2.3 Losses

Each model cell was assigned a Manning's "*n*" (surface roughness), initial loss and a continuing loss based on land use types and importantly hydrological characteristics. Table 3-3 summarises the adopted roughness and loss parameters. It should be noted these parameters were adopted based on the calibration to a historic event where streamflow gauges were present in other Whangarei District catchment (i.e. M01, M13, M14 and M15). Figure 3-3 displays the roughness layer based on the land use type, showing most land use is forest and grassland.



TABLE 3-3 DESIGN MODEL PARAMETERS

Hydrological areas	Land use types	Manning's n	Initial loss (IL) – mm	Continuing loss (CL) – mm/hr
Entire M02 catchment	Forest	0.08	34	5.3
	Grassland	0.06	34	5.3
	Cropland – perennial	0.04	20	2
	Cropland – annual	0.04	20	2
	Wetland – open water	0.04	0	0
	Wetland – vegetated	0.05	10	1
	Urban areas	0.10	5	1.5
	Waterways	0.06	0	0
	Other	0.06	15	1.5

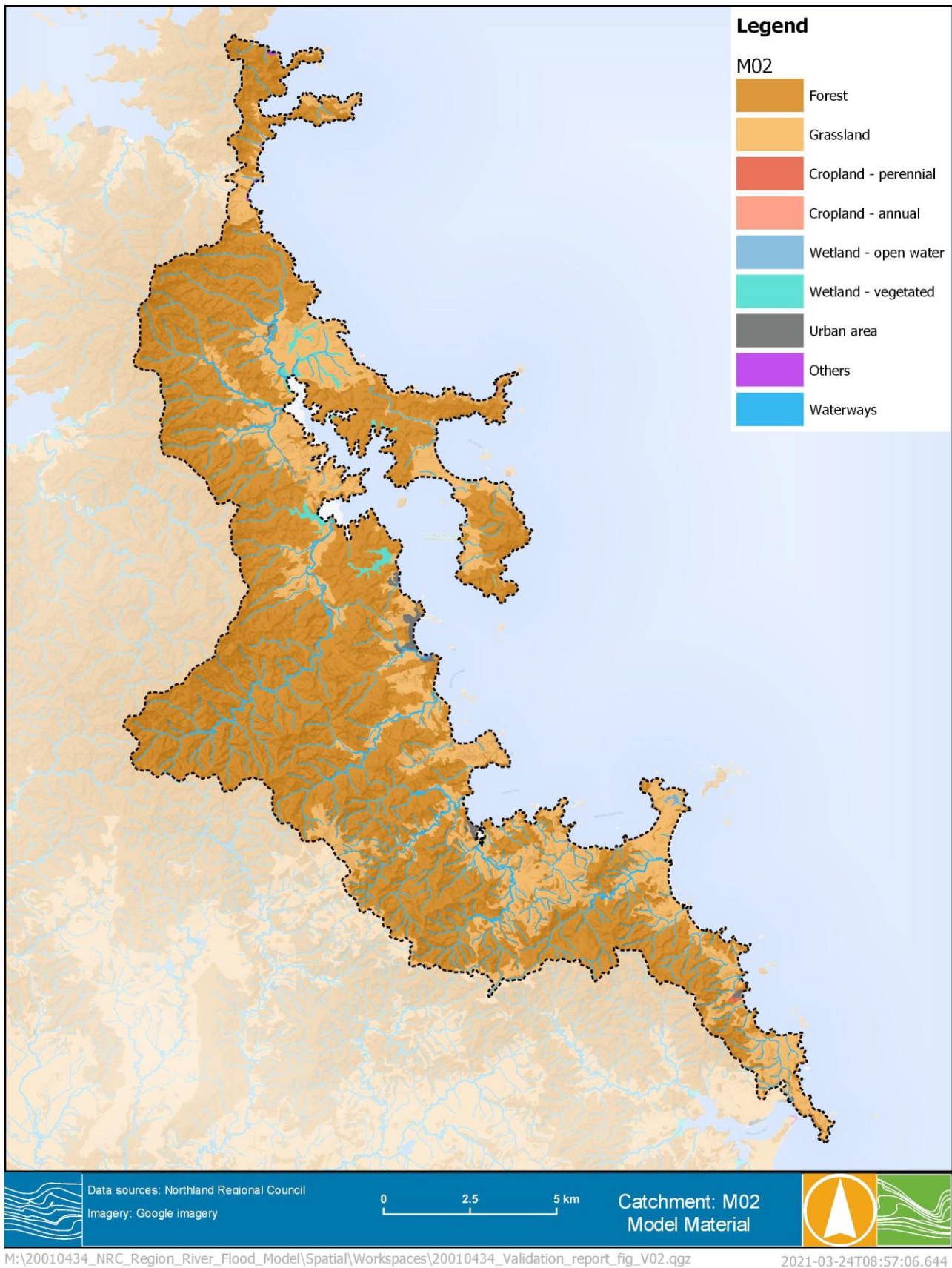


FIGURE 3-3 HYDRAULIC MODEL MATERIAL LAYER



3.2.4 Boundaries

As the Oakura catchment is a coastal catchment, a static tail-water (i.e. 1390 mm OTP) outflow boundary based on the 2 year ARI tide level³ at Marsden Point was used for the design modelling. A 1.2 m sea level rise was adopted for climate change runs based on the project brief.

There is no upstream inflow coming from upstream catchments applied in this catchment model.

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³ MWH, 2010 *Priority Rivers – Flow Assessment, Sea Level Rise and Storm Surge*, prepared for Northland Regional Council



4 MODELLING RESULTS

4.1 Modelled Result Processing/Filtering

Design modelling consisted of running the model for four storm durations (1-hour, 6-hour, 12-hour and 24-hour) with the results enveloped for each design event (i.e. 1%, 2% and 10% AEP) to ensure the critical duration was well represented across each part of the catchment. Each model run produced gridded results, including depth, water surface elevation (WSE), flood hazard (Z0) and velocity. Several post-processing steps were required to produce the final design modelling outputs. These are described as follows:

Step 1:

- The modelling results are firstly merged to produce a single data set for each AEP from the storm durations modelled. For example, the flood depth output is produced by merging the depth results of the four different durations within each AEP. This allows for the critical storm duration across each part of the catchment to be represented (i.e. the short intense storms in upper reaches and longer duration storms in the lower parts of the catchment).

Step 2:

- The maximum gridded results are then remapped to a finer DEM grid using LiDAR data resampled to a 5-m grid resolution. This allows the flood extent to be more accurately displayed on the map and the higher resolution gridded results (i.e. same resolution as the 5-m DEM) to be produced.

Step 3:

- Finally, the remapped results are post-processed by filtering out depths below 100mm and puddle areas less than 2000m² as agreed with NRC.

Figure 4-1, Figure 4-2 and Figure 4-3 respectively show the final post-processed flood depths, velocity and hazard of the 1% AEP design event modelled for M02. Figure 4-4 shows the flood depth map zoomed in at a township (Oakura) as an example. It is noted that the hazard classification is based on the following criteria:

TABLE 4-1 FLOOD HAZARD CLASSIFICATION

Hazard classification	Hazard – VxD (m ² /s)
Low	< 0.2
Low to Moderate	0.2 to 0.4
Moderate	0.4 to 0.6
Moderate to High	0.6 to 0.84
High	> 0.84

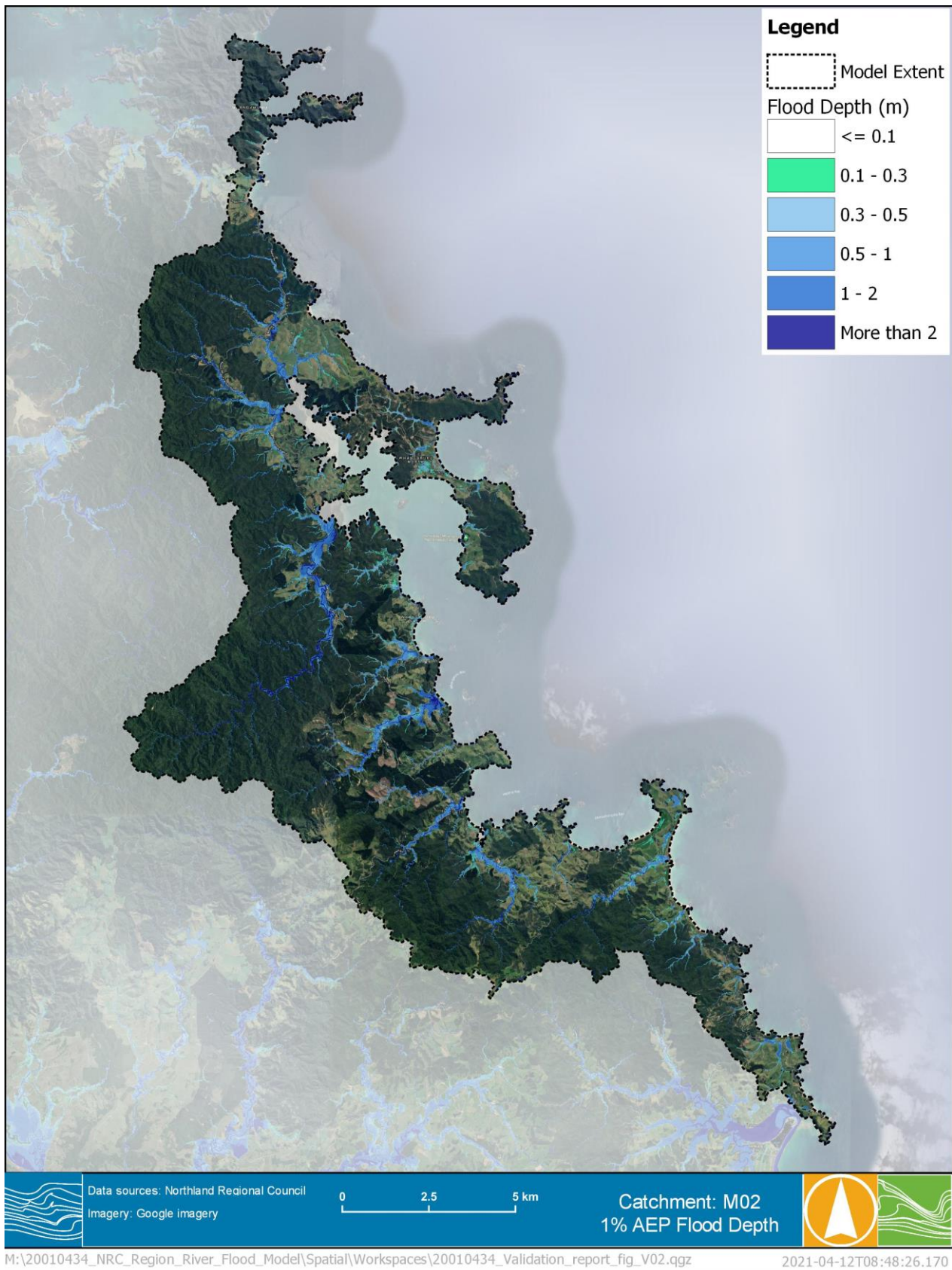


FIGURE 4-1 DESIGN MODELLING OF 1% FLOOD DEPTH

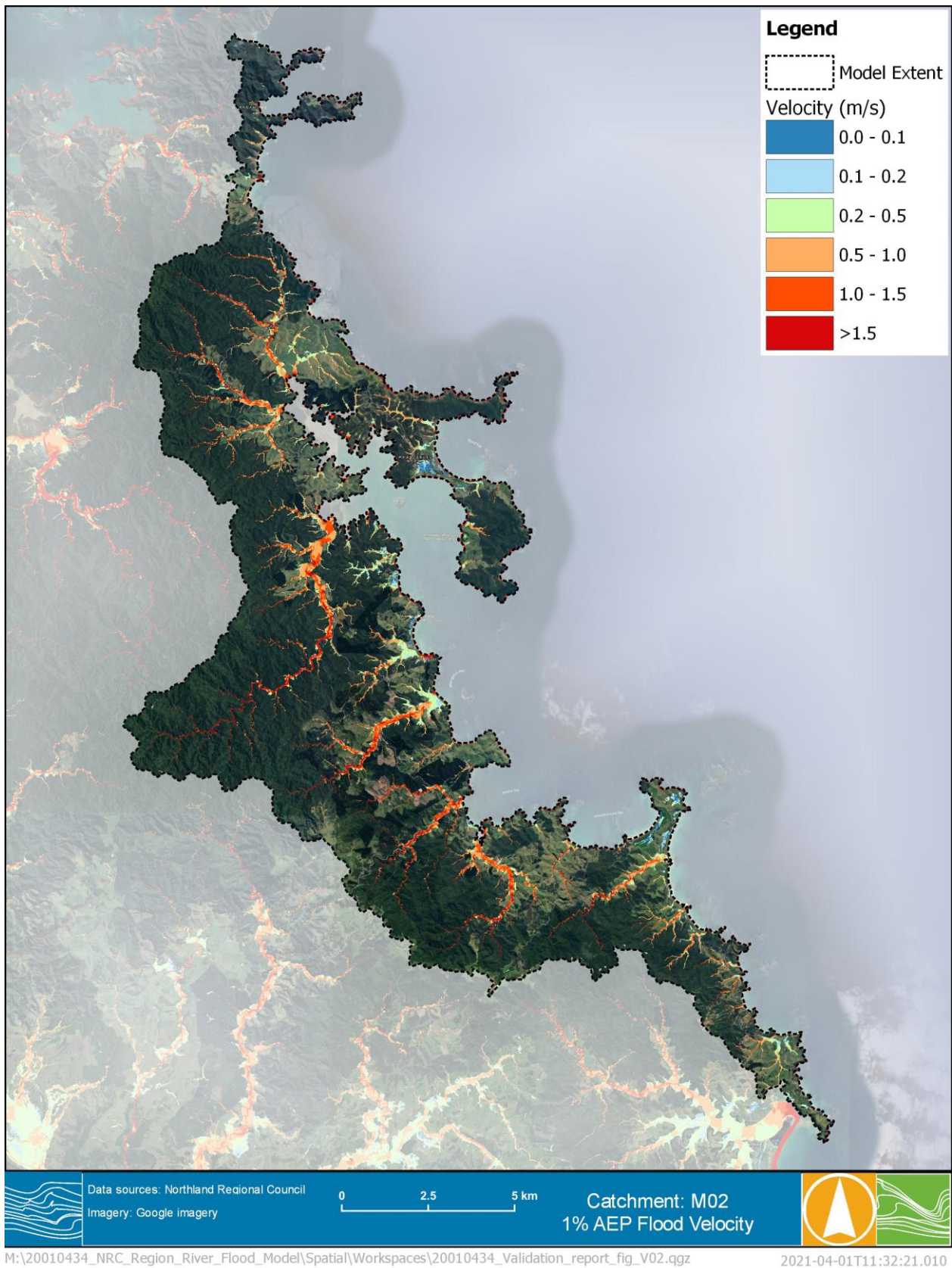


FIGURE 4-2 DESIGN MODELLING OF 1% AEP FLOOD VELOCITY

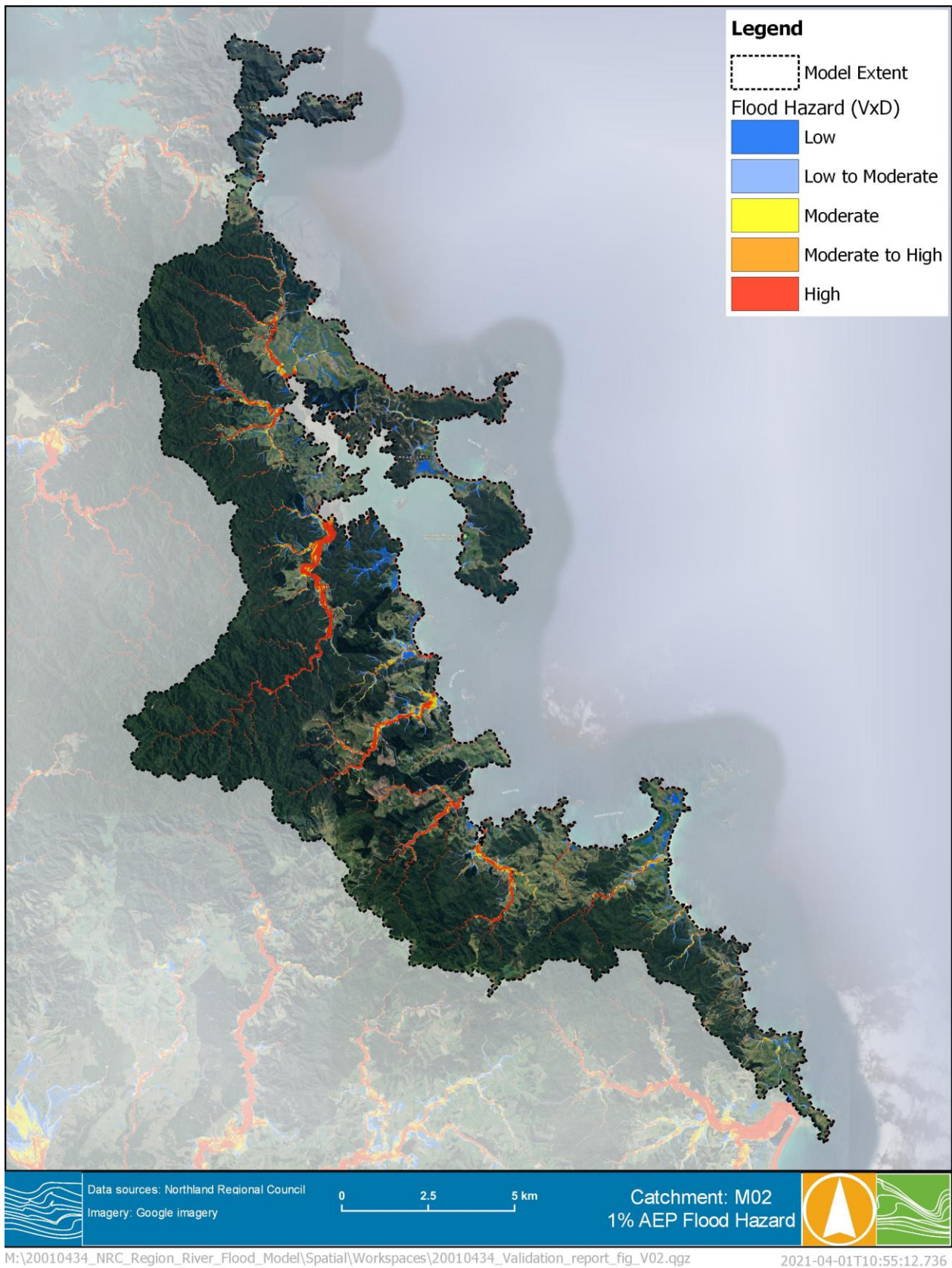


FIGURE 4-3 DESIGN MODELLING OF 1% AEP FLOOD HAZARD

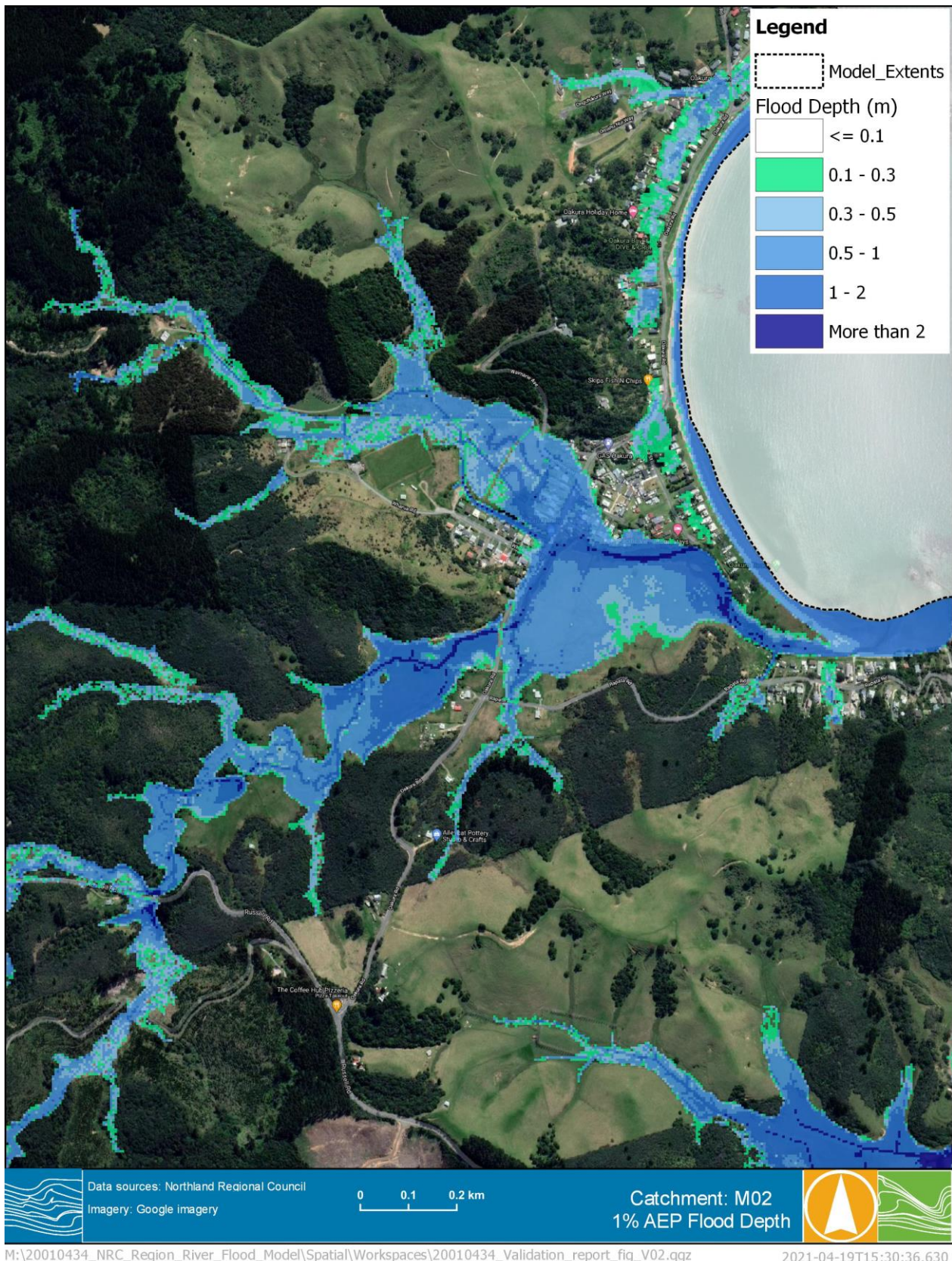


FIGURE 4-4 DESIGN MODELLING OF 1% AEP FLOOD DEPTH ZOOMED AT OAKURA



5 VERIFICATION OF DESIGN FLOWS

Flow lines were included at several waterways in the hydraulic model as 2D Plot Outputs (2D PO) for design events. This allows flow hydrographs and peak flows to be extracted at these locations. Figure 5-1 displays the PO line locations and shows that there is no streamflow gauge found within the Oakura catchment.

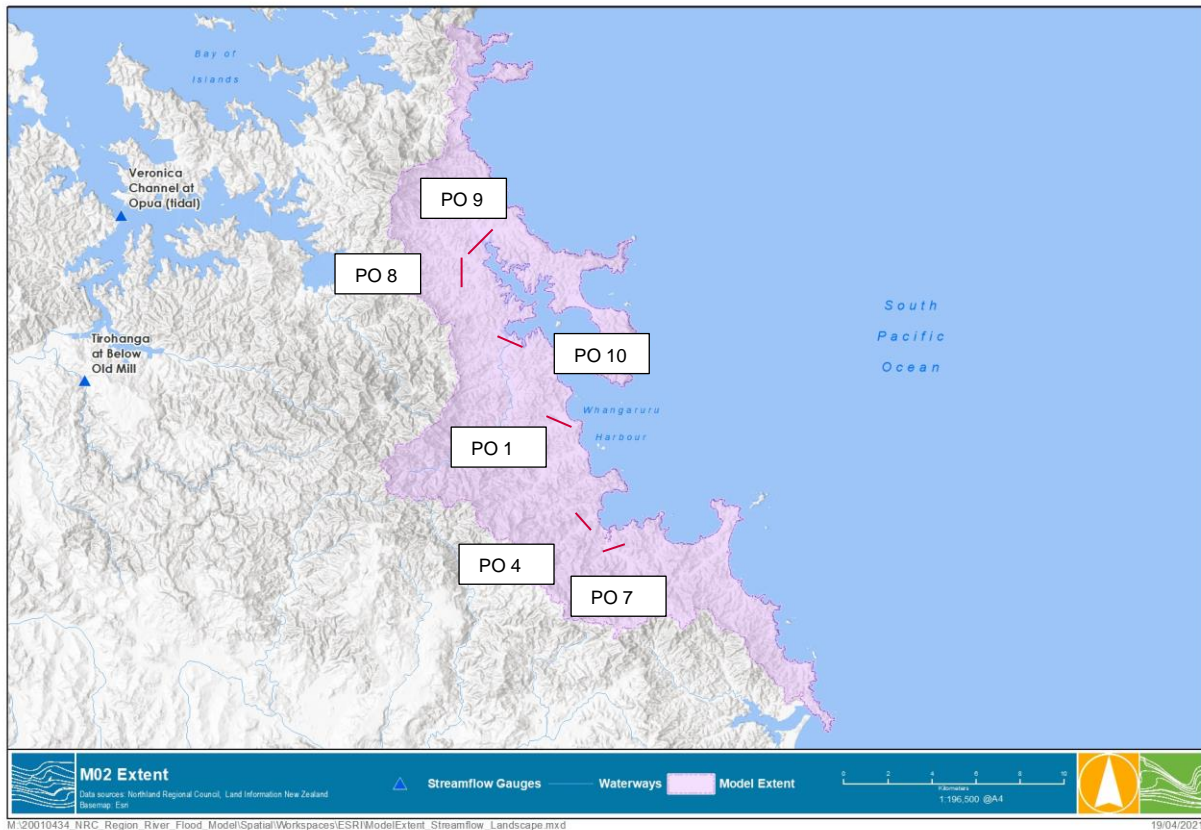


FIGURE 5-1 AVAILABLE STREAMFLOW GAUGES WITHIN OAKURA CATCHMENT

The modelled peak flow for the 1% AEP design flood was compared with hydrological estimates, including the Rational Method and SCS Method.



5.1 Regional Estimation Methods

For catchments where a suitable streamflow gauge record was not available, additional estimation methods were used to provide design flow verification. These methods are based on empirical estimations using catchment area and design rainfall totals to estimate peak design flows. These methods were checked for each Flow Line location within the study area and are described below.

5.1.1 NIWA New Zealand River Flood Statistics Portal

The New Zealand River Flood Statistics portal⁴ provides peak flood estimation at streamflow gauging stations and the entire river system in New Zealand completed in 2018. The design estimates can be extracted from the portal are:

- Flood Frequency estimates, noted as Henderson & Collins 2018 (at river reach).
- Rational Method HIRDS V3 (at river reach).

The flood frequency estimates given by the portal are determined using the Mean Annual Flow method developed by Henderson & Collins (2018)⁵.

5.1.2 SCS method

The Soil Conservation Service (SCS) method, first developed by the U.S. Department of Agriculture's Soil Conservation Service, calculates peak flood flow based on rainfall and land-cover-related parameters. It is the recommended method for stormwater design in the Auckland region, providing a useful comparison. The peak flow equation is:

$$Q = (P - I_a)^2 / (P - I_a + S)$$

where:

- Q is run-off depth (millimetres).
- P is rainfall depth (millimetres)
- S is the potential maximum retention after run-off begins (millimetres).
- I_a is initial abstraction (millimetres), which is 5 millimetres for permeable areas and zero otherwise.

The retention parameter S (measured in millimetres) is related to catchment characteristics through:

$$S = (1000/CN - 10) 25.4.$$

The value of the curve number (CN) represents the run-off from 0 (no run-off) to 100 (full run-off) and it is influenced by soil group and land use. A CN value of 50 was used for the SCS estimation of this catchment.

The run-off depth (Q) is then converted to a peak flow rate using the SCS unit hydrograph.

⁴ NIWA Flood Frequency tool, accessed via: <https://niwa.co.nz/natural-hazards/hazards/floods>

⁵Henderson, R.D., Collins, D.B.G., Doyle, M., Watson, J. (2018) *Regional Flood Estimation Tool for New Zealand Final Report Part 2*. NIWA Client Report



5.1.3 Rational Method

The Rational Method is widely used across both New Zealand and Australia. The equation is based on catchment area and design rainfall. The equation is:

$$Q = C i A / 3.6$$

where:

- Q is the estimate of the peak design discharge in cubic metres per second
- C is the run-off coefficient
- i is rainfall intensity in mm/hr hour, for the time of concentration
- A is the catchment area in km².

5.2 Verification Results

Table 5-1 summarises the comparison of 1% AEP peak flow estimates with the modelled values at six PO line locations in the Oakura catchment and the differences between the estimation methods and modelled results can be visualised in Figure 5-2.

The Rational Method and the SCS method tend to underestimate the design flows across these PO locations when compared with the modelled design flows at these PO locations which have a good match to the HIRDS V3 Rational Method from NIWA.

The verification of the modelled design flows heavily relied on the use of empirical method estimations. With the absence of streamflow gauge, this catchment model was not able to be calibrated and its results were not verified against any historic record, however the results are fit for purpose including the of mapping riverine flood hazard zones across the entire Northland region and update existing flood intelligence.



TABLE 5-1 SUMMARY OF 1% AEP PEAK FLOW COMPARISON

PO line location	Hydraulic model (m³/s)		Empirical estimates (m³/s)		NIWA Flood Frequency Tool 2018 (m³/s)	
	Critical duration	Modelled peak	SCS	Rational method	NIWA – Rational method	NIWA – H&C 2018
PO9	6 hr	131.3	35.7	33.0	115.7	25
PO8	1 hr	118.0	44.5	75.6	122.5	24
PO10	6 hr	346.6	102.1	93.1	227.5	103
PO1	6 hr	35.3	9.7	8.8	48.1	9
PO4	1 hr	132.9	37.4	62.9	113.2	37
PO7	6 hr	167.2	36.0	32.3	131.2	41

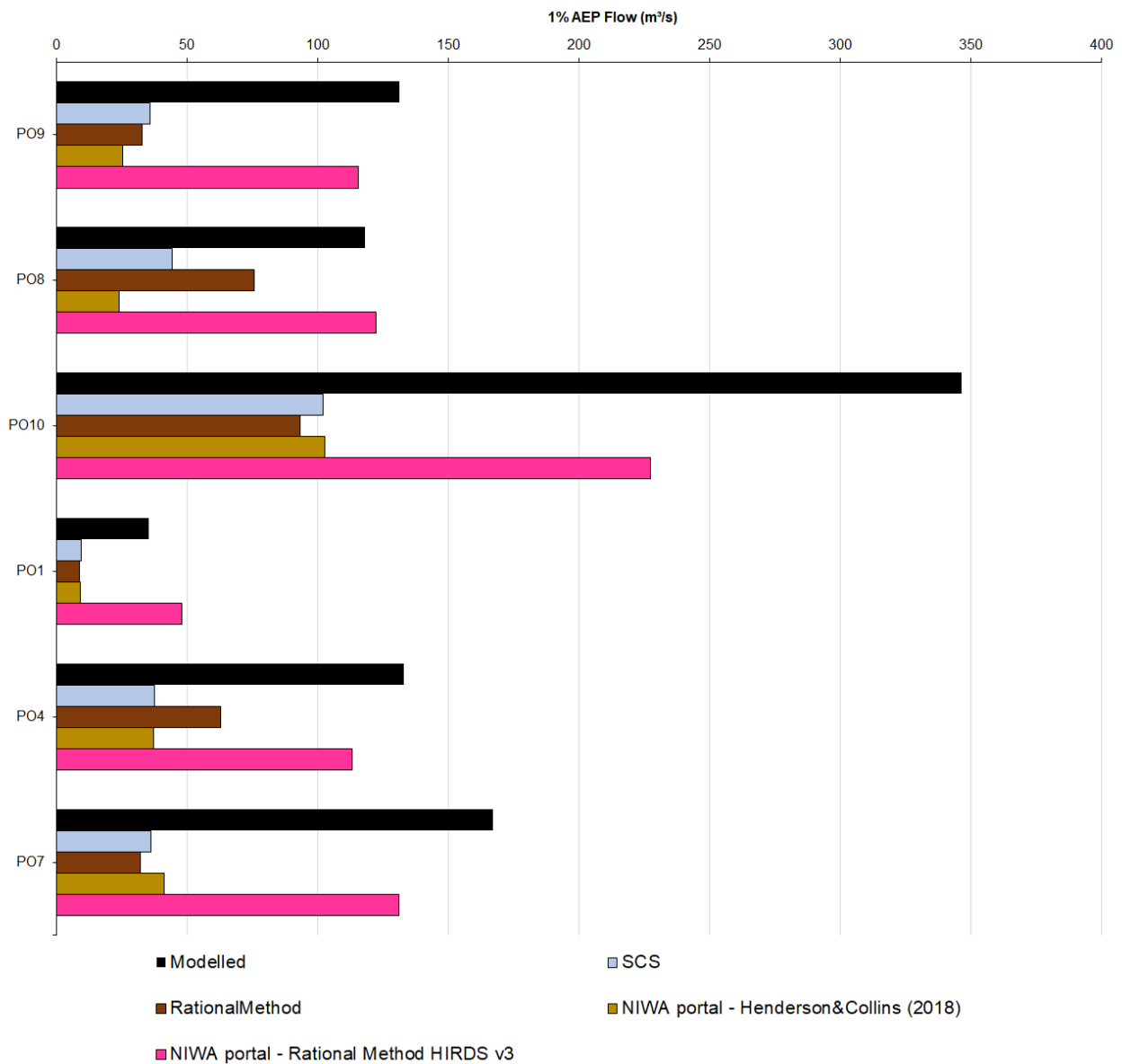


FIGURE 5-2 VERIFICATION OF DESIGN MODELLING RESULTS AGAINST HYDROLOGICAL ESTIMATES



6 SUMMARY

The Oakura catchment model (M02) was not calibrated and its model parameters were adopted based on calibrated catchments nearby (i.e. M01, M13, M14 and M15) in the Whangarei District. The design modelling of this catchment consisted of four storm durations (1-hour, 6-hour, 12-hour and 24-hour) for each design AEP (i.e. 1%, 2% and 10% AEP). Design flood extents and gridded results, including depth, water surface elevation, velocity and hazard were produced and delivered to NRC.

The modelled 1% AEP design flows were verified against limited design flood estimation methods at six PO line locations. The modelled design flows have a reasonably good match to the HIRDS V3 Rational method from NIWA. The absence of historic records and the general limitation with empirical design estimates reduce the reliability of the verification.

When considering the scope and the scale of this project, the current modelling results are considered fit for use. Modelling outputs can be used to identify flood hazard and potential flood risk. It can also inform planning decisions, infill flood mapping between detailed flood studies and provide a basis for broad emergency management exercises.

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